



**Demo Day**

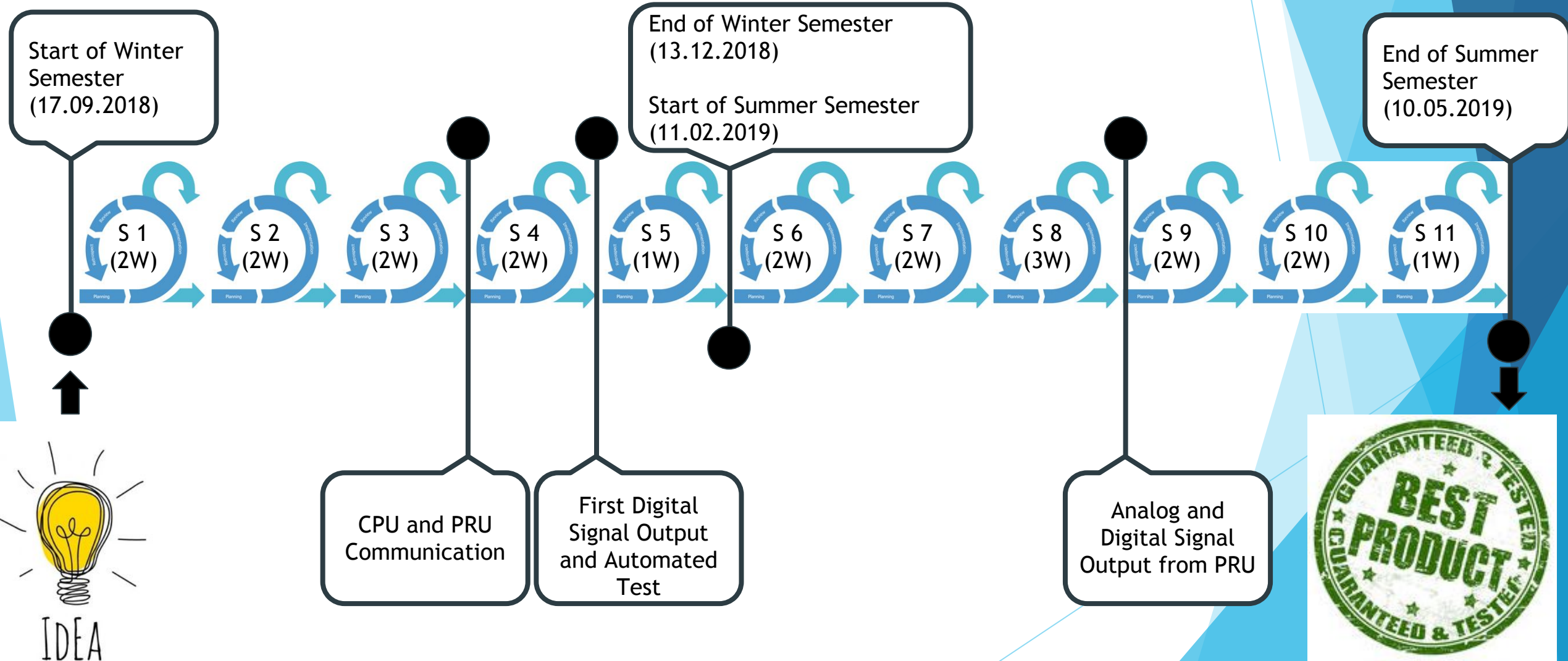
# Introduction

- ▶ Team members
- ▶ Team Web Page:  
<http://labss2.fiit.stuba.sk/TeamProject/2018/team15iss-it/>
- ▶ Team GIT: <https://git.kistler.com/FIIT/iotester/tree/master>
- ▶ Contact: [fiit.tp.tim15@gmail.com](mailto:fiit.tp.tim15@gmail.com)

# Vision and Mission - Project Goals

- ▶ Team Goals:
  - ▶ SCRUM
  - ▶ Collaboration
  - ▶ Teamwork
- ▶ Product Owner Goals:
  - ▶ Design and implementation of device for automatic testing
  - ▶ Integration to existing framework (Robot Framework)

# Vision and Mission - Start vs. End

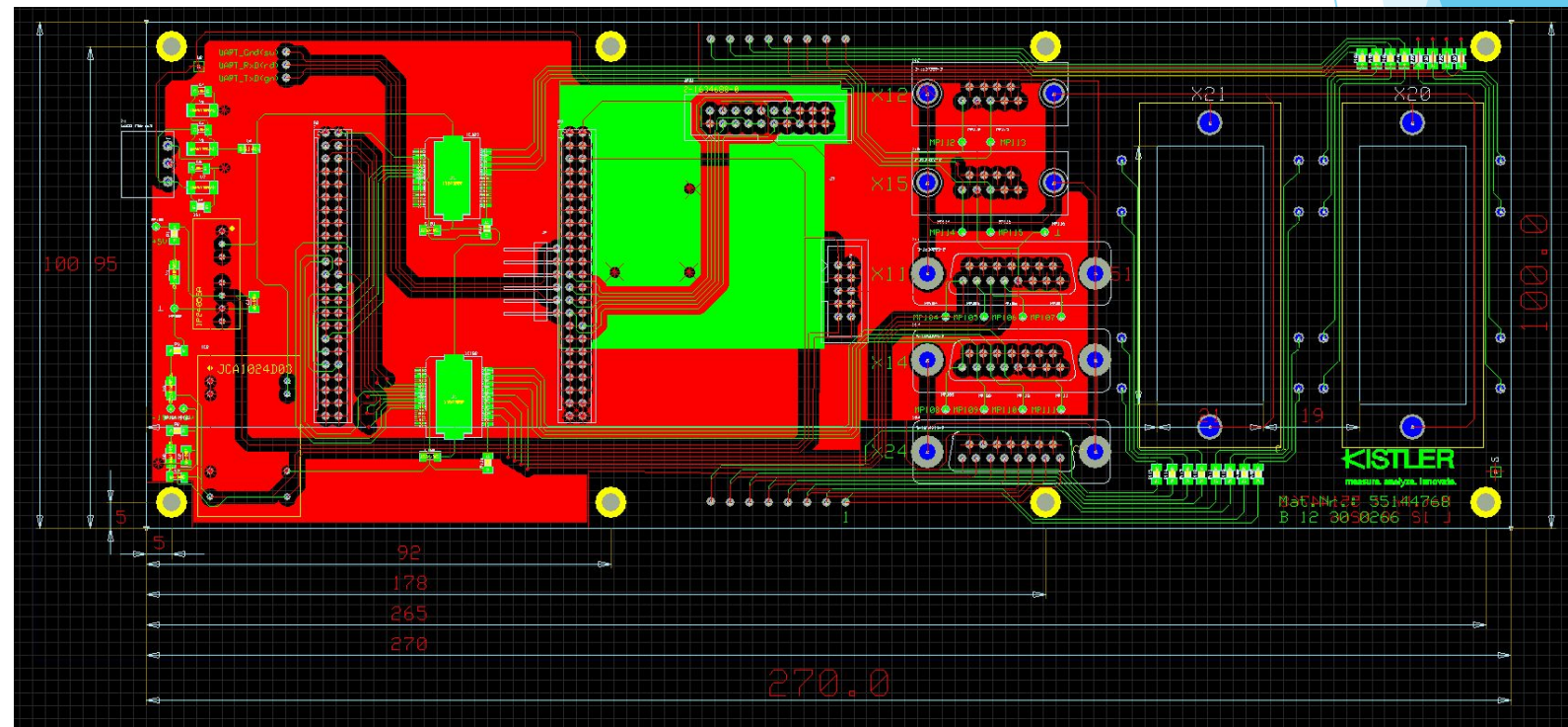


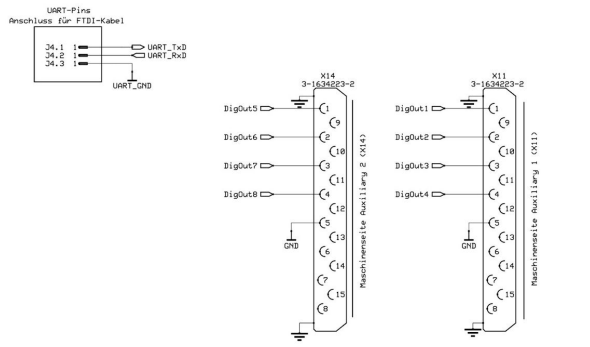
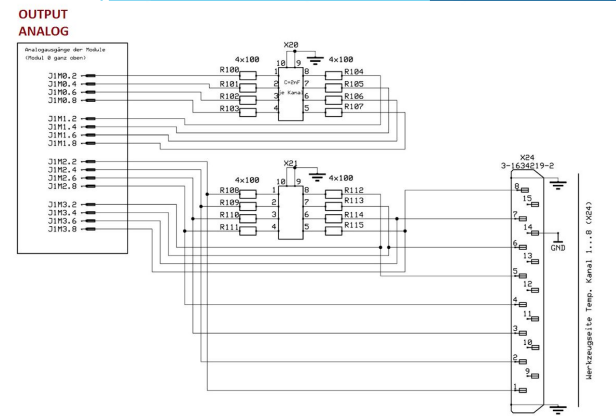
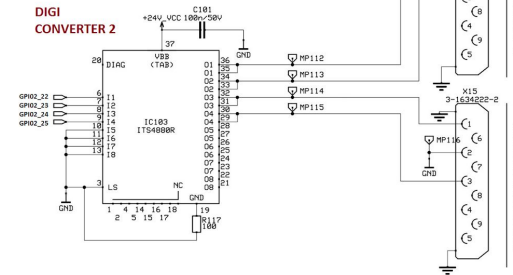
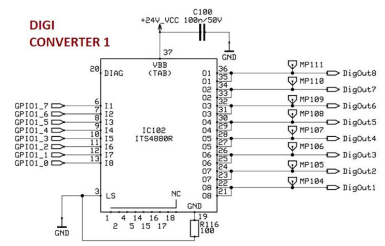
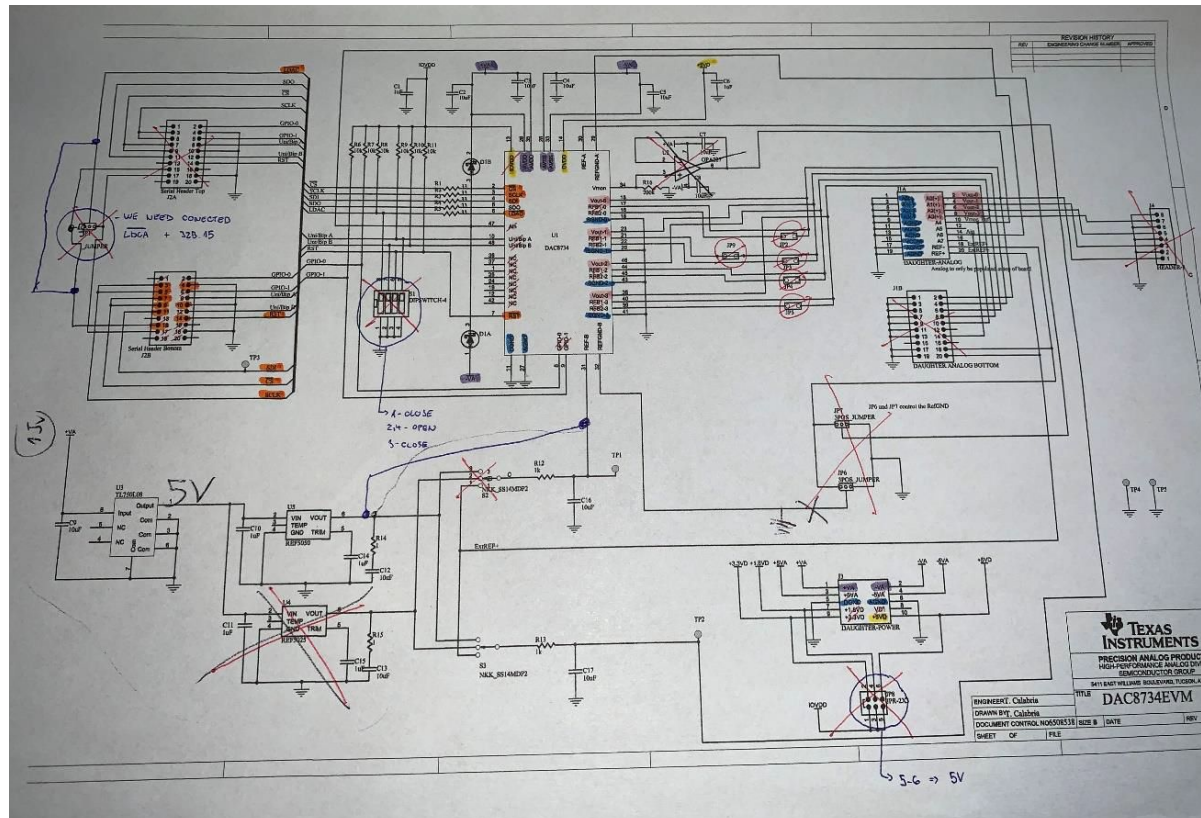
# Technical Specification - Software

- ▶ IDE - Code Composer
- ▶ Source codes in C language - compilation is needed
- ▶ Web Server - Flask
- ▶ Robot Framework
  - ▶ Digital Input
  - ▶ Python library for sending json

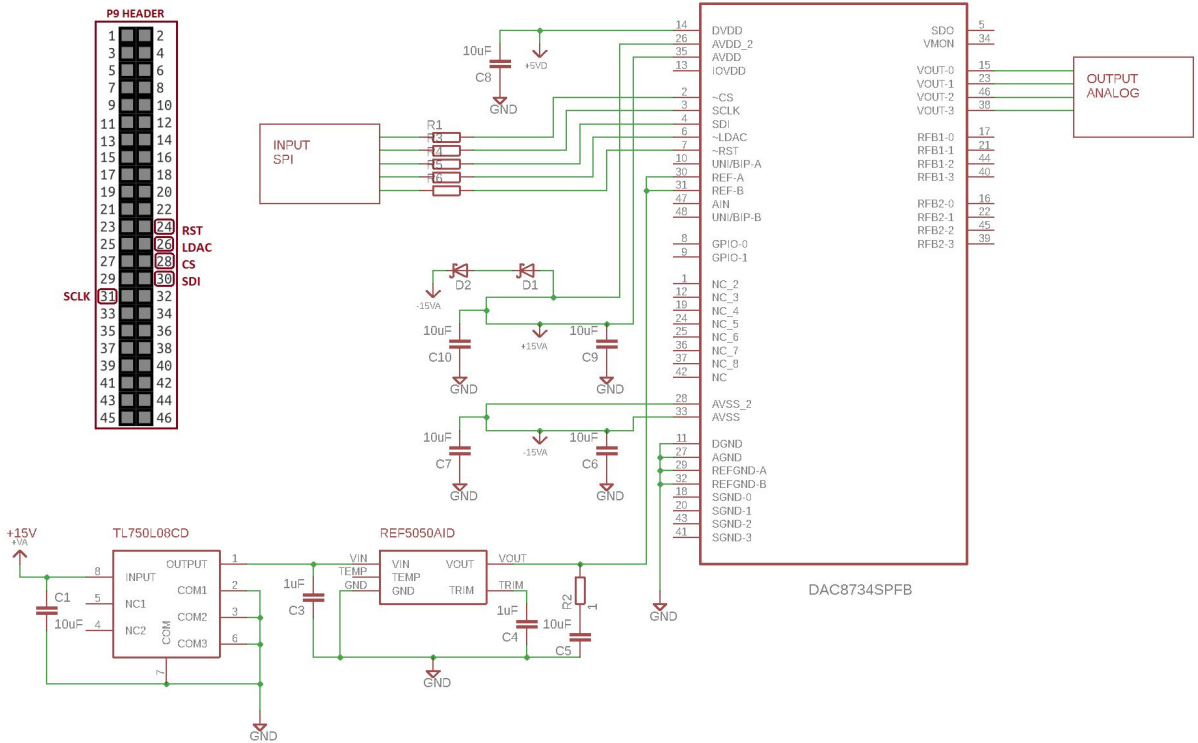
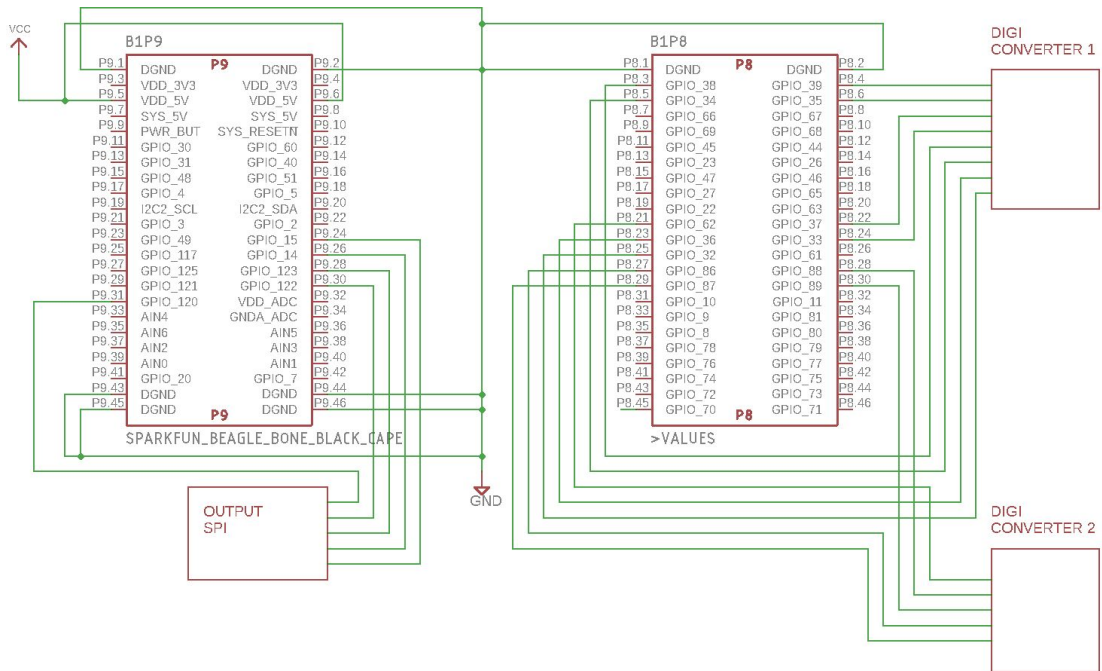
# Technical Specification - Hardware

- ▶ To do:
  - ▶ analyze the hardware
  - ▶ create new prototype design
  - ▶ create documentation



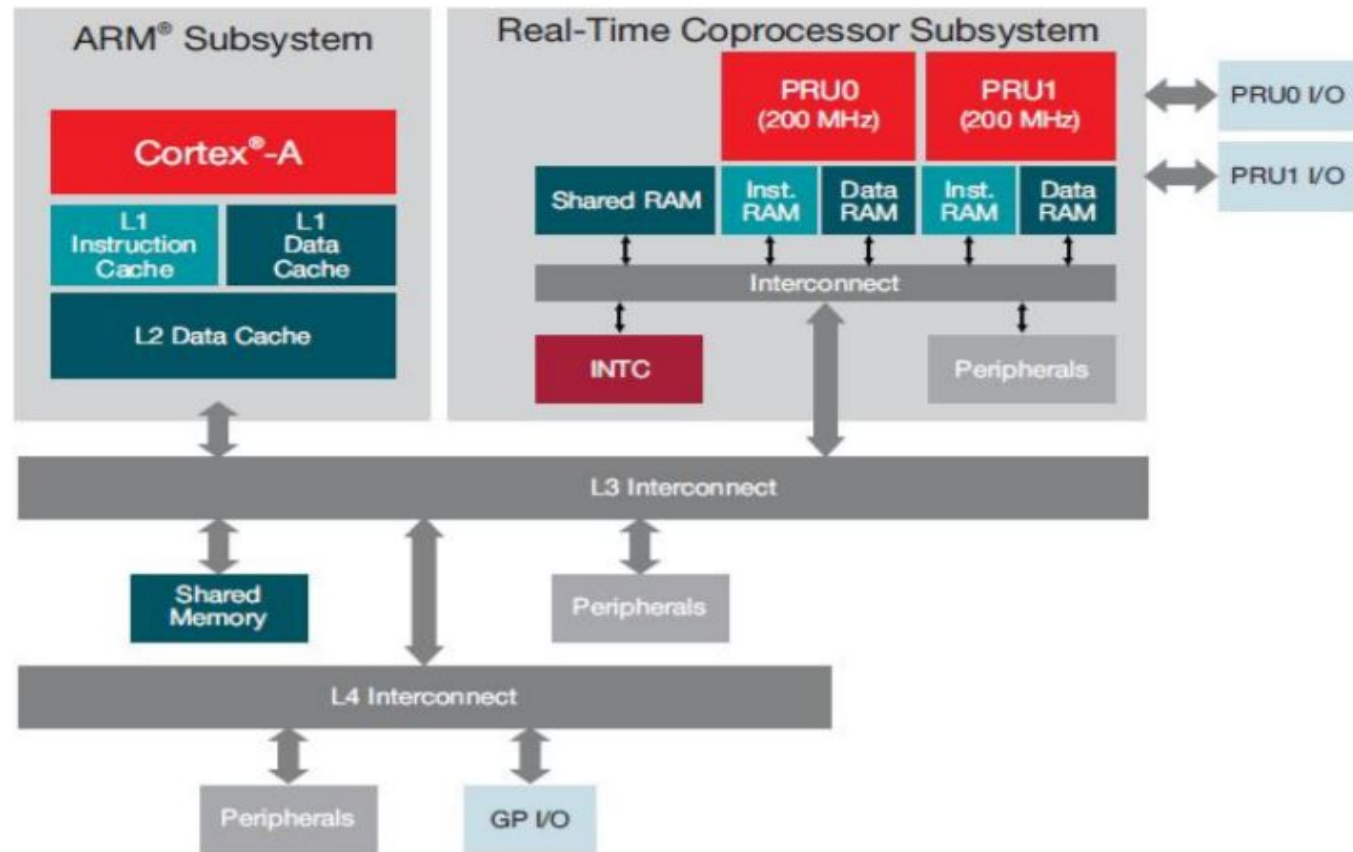


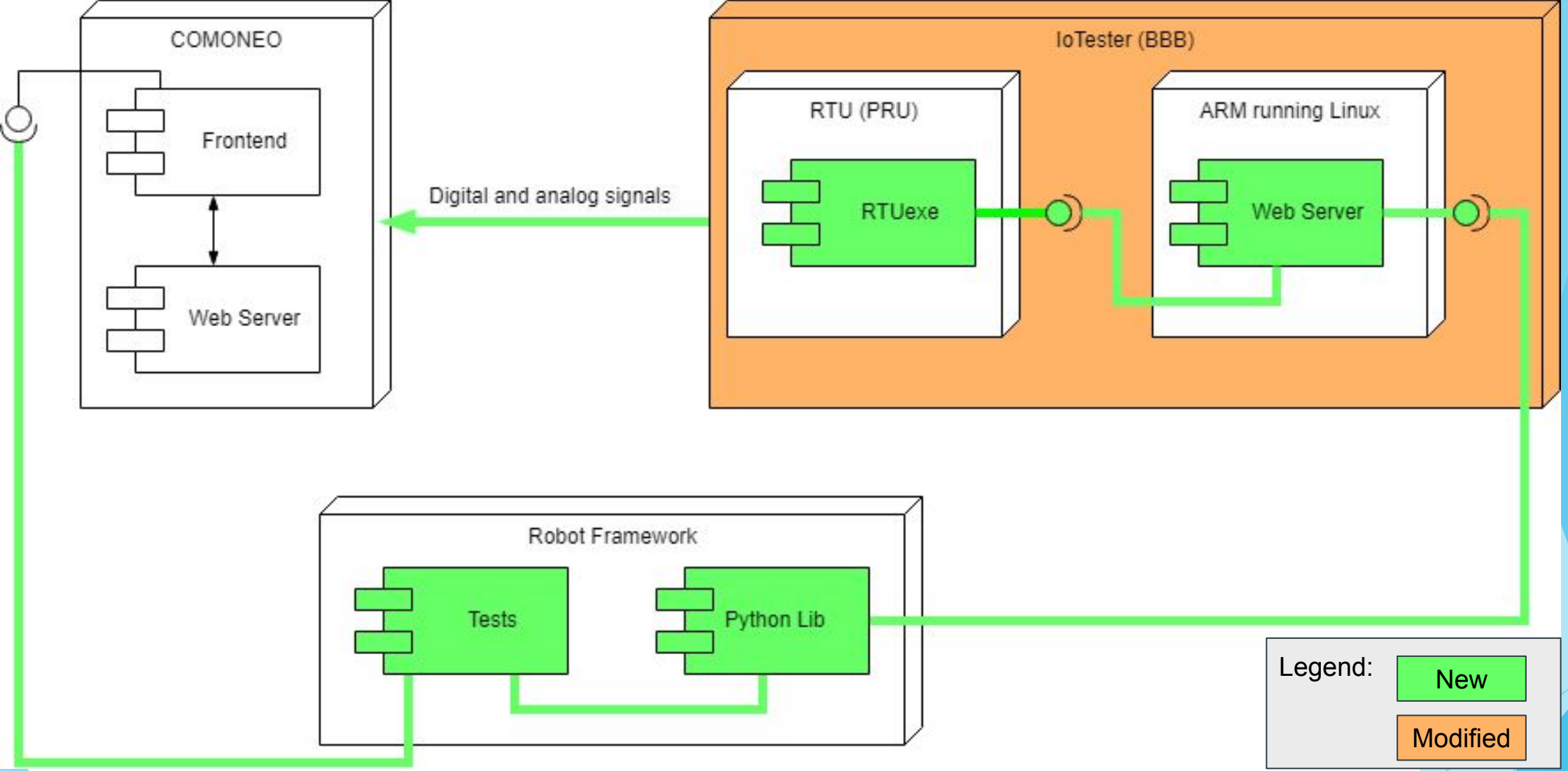
P9		P8	
GND	1	GND	1
3.3V	3	3.3V	4
5V Raw	5	5V Raw	6
5V	7	5V	8
	9		10
l4 RX/GPIO0_30	11	GPIO1_28	12
l4 TX/GPIO0_31	13	PWM1A/GPIO1_18	14
GPIO1_16	15	PWM1B/GPIO1_19	16
GPIO0_5	17	GPIO0_4	18
GPIO0_15	19	GPIO0_14	20
l2 TX/GPIO0_3	21	Serial2 RX/GPIO_2	22
GPIO1_17	23	Serial1 TX/GPIO_12	24
GPIO3_21	25	Serial1 RX/GPIO_13	26
GPIO3_19	27	GPIO3_16	28
GPIO3_15	29	GPIO3_16	30
GPIO3_14	31	VDD_ADC	32
AIN4	33	GND_ADC	34
AIN6	35	AIN5	36
AIN2	37	AIN3	38
AIN0	39	AIN1	40
GPIO0_20	41	GPIO0_7	42
GND	43	GND	44
GND	45	GND	46
		Serial5 TX/GPIO_14	37
		GPIO1_6	4
		GPIO1_2	5
		GPIO2_2	7
		GPIO2_5	9
		GPIO1_13	11
		PWM2B/GPIO0_23	13
		GPIO1_15	15
		GPIO0_27	17
		PWM2A/GPIO0_22	19
		GPIO1_30	21
		GPIO1_4	23
		GPIO1_0	25
		GPIO2_22	27
		GPIO2_23	29
		GPIO0_10	31
		GPIO0_9	33
		GPIO0_8	35
		GPIO2_12	39
		GPIO2_10	41
		GPIO2_8	43
		GPIO2_6	45
		GPIO1_7	4
		GPIO1_3	5
		GPIO2_3	7
		GPIO2_4	10
		GPIO1_12	12
		GPIO0_26	14
		GPIO1_14	16
		GPIO2_1	18
		GPIO1_31	20
		GPIO1_5	22
		GPIO1_1	24
		GPIO1_29	26
		GPIO2_24	28
		GPIO2_25	30
		GPIO0_11	32
		GPIO2_17	34
		GPIO2_16	36
		Serial5 RX/GPIO15	38
		GPIO2_13	40
		GPIO2_11	42
		GPIO2_9	44
		GPIO2_27	46

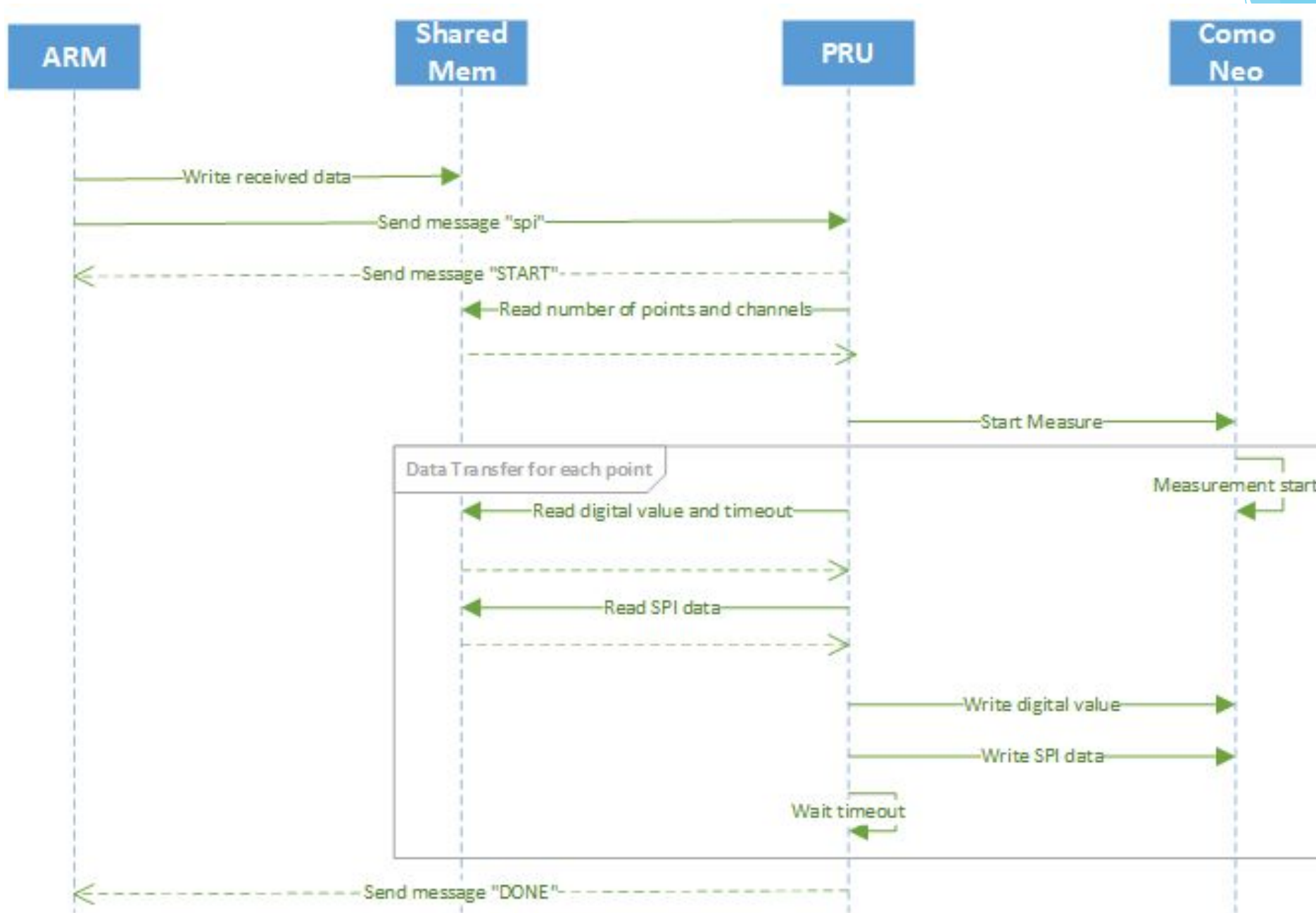




# Technical Specification - Hardware (Architecture of ARM/PRU)







# Solution - Data for BBB

- ▶ Data structure, which represents data that is sent to BBB:

```
std::uint32_t sampleIndex; ///< Index of sample in the cycle.
```

```
std::uint32_t digitalIn; ///< Status of digital inputs.
```

```
std::int32_t channel[cChannelsInSample]; ///< max 16 channels
```

- ▶ JSON structure:

```
"sampleIndex": "0",
```

```
"digitalIn": "256",
```

```
"channel": ["0", "-2751", "-1566", "-1190", "-2775", "-24", "- 88", "-588", "477", "0", "0", "0", "0", "0", "0", "0"]
```



# Solution - Hardware

- ▶ Build dependencies packages with Yocto
- ▶ Boot from SD card
- ▶ Setup PINs to desired modes

Head_pin	\$PINS	ADDR/OFFSET	Name	GPIO NO.	Mode3
P9_28	103	0x99c/19c	SPI1_CS0	113	spi1_cs0
P9_29	101	0x994/194	SPI1_D0	111	spi1_d0
P9_30	102	0x998/198	SPI1_D1	112	spi1_d1
P9_31	100	0x990/190	SPI1_SCLK	110	spi1_sclk

Head_pin	\$PINS	ADDR/OFFSET	GPIO NO.	Name	Mode7
P8_01				DGND	
P8_02				DGND	
P8_03	6	0x818/018	38	GPIO1_6	gpio1[6]
P8_04	7	0x81c/01c	39	GPIO1_7	gpio1[7]
P8_05	2	0x808/008	34	GPIO1_2	gpio1[2]
P8_06	3	0x80c/00c	35	GPIO1_3	gpio1[3]
P8_07	36	0x890/090	66	TIMER4	gpio2[2]
P8_34	51	0x8cc/0cc	81	UART3_RTSN	gpio2[17]
P8_36	50	0x8c8/0c8	80	UART3_CTSN	gpio2[16]
P8_37	48	0x8c0/0c0	78	UART5_TXD	gpio2[14]
P8_38	49	0x8c4/0c4	79	UART5_RXD	gpio2[15]

# Solution - PRU

- ▶ PRU-ICSS Remoteproc and RPMsg - messages
- ▶ Loading PRU program
  - ▶ `echo 'am335x-pru0-fw' > /sys/class/remoteproc/remoteproc1/firmware`
- ▶ Run PRU program
  - ▶ `echo 'start' > /sys/class/remoteproc/remoteproc1/state`
- ▶ Stop PRU program
  - ▶ `echo 'stop' > /sys/class/remoteproc/remoteproc1/state`
- ▶ Send message
  - ▶ ARM => PRU
    - ▶ `echo "test30" > /dev/rpmsg_pru30`
  - ▶ PRU => ARM
    - ▶ `pru_rpmsg_send(&transport, dst, src, "START", 5);`
- ▶ "pru\_iep.h" library for timing

# Solution - PRU

- ▶ Execution steps:
  - ▶ Data are stored in memory
  - ▶ Fetch message “spi”
  - ▶ Read data from memory
  - ▶ Start measurement
  - ▶ Write data to SPI in cycle
  - ▶ Write digital data
  - ▶ Timing with register IEP (1 time period = 62,5 us)
  - ▶ Writing all points



# Solution - Obstacles

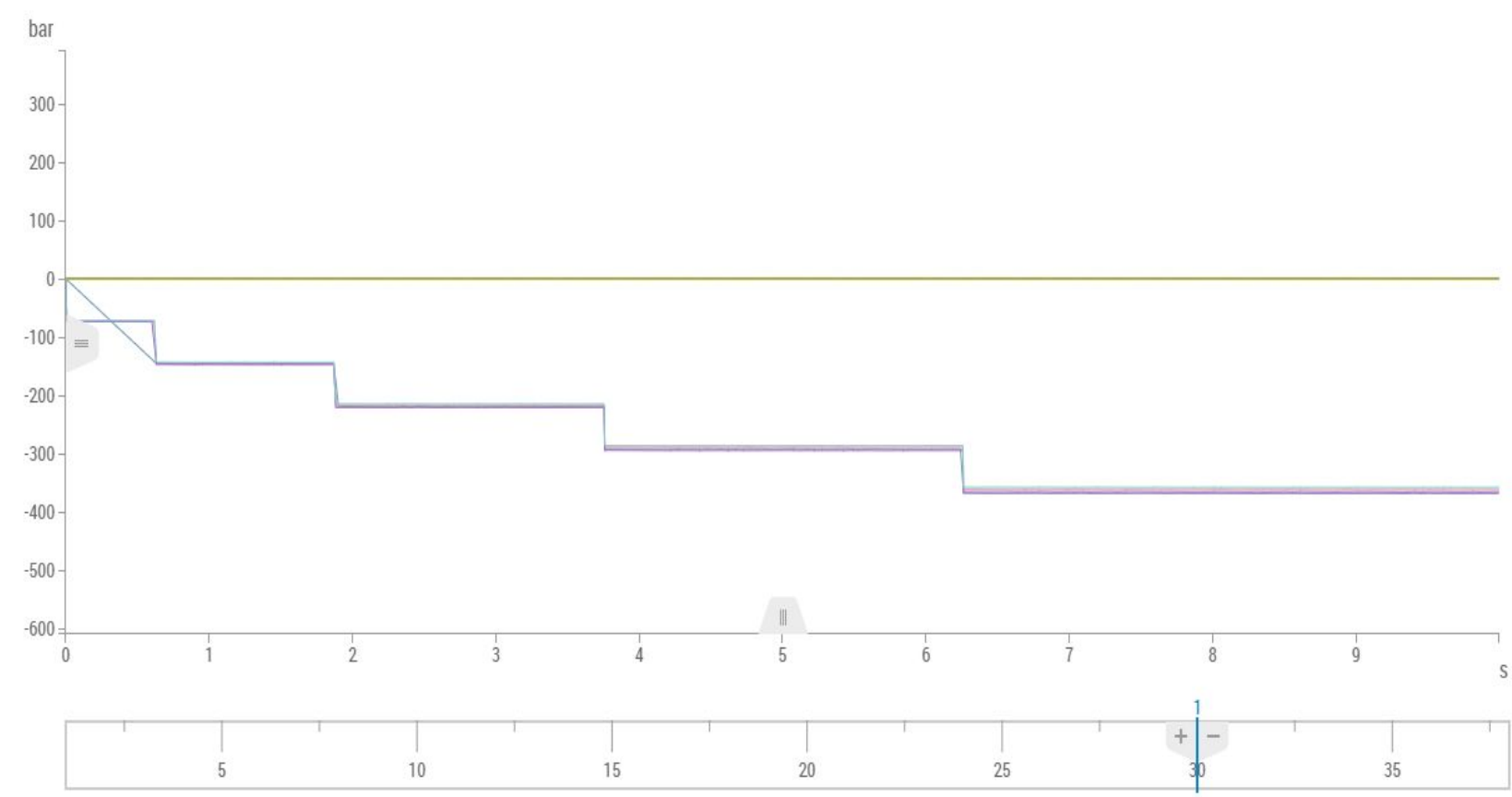
- ▶ Usage of PRU-ICSS Remoteproc and RPMsg
  - ▶ Loss of BBB Linux OS.
  - ▶ Missing packages
  - ▶ Hard to debug
  - ▶ Can't do standard boot from SD card
  - ▶ Less advantages with lot of problems

- Home
- Analysis
  - Trend
  - Cycle
  - Delta Time
- Monitoring
- Control
- Mould
- Device
- Maintenance

Cycle View Reference

Analysis > Cycle > Cycle View

Cycle 30 May 2, 2019 9:22:51 AM



Graph settings Cursor Comments

Cavity Display Highlight

01	02	03	04
05	06	07	08
09	10	11	12
13	14	15	16

Sensors Pressure Temperature

PostGate

Machine Signal

1 eSwitchOverPoint1

Visualisation Options

Evaluation Objects ----- show current

Reference ----- None

Create Reference

Colouring ----- colour per cavity

# Discussion Time

